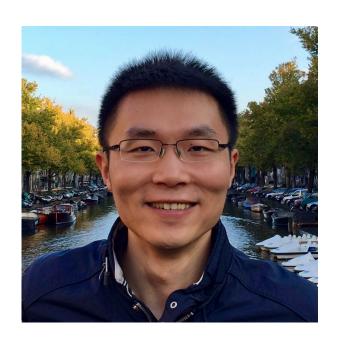


IARPA Video LINCS Proposers' Day Lightning Talk
Jia Deng
Princeton University
Feb 7, 2024

#### PI: Jia Deng



- Associate Professor
- Department of Computer Science
- Princeton University
- jiadeng@princeton.edu
- Lab: https://pvl.cs.princeton.edu

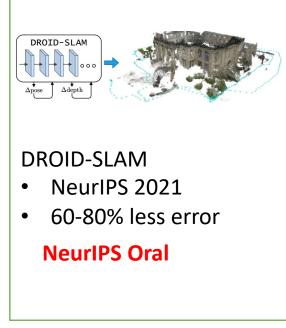
#### Capability 1: 3D Reconstruction

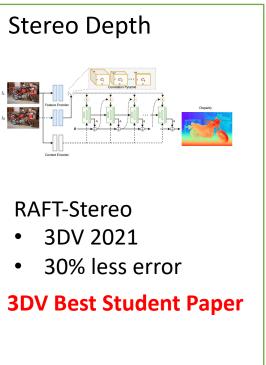
SLAM

- Optimization-inspired neural networks (neural + classical)
  - Recurrent neural networks + differentiable optimization layers
  - Large improvements over prior SOTA on many 3D vision tasks

# Optical Flow RAFT • ECCV 2020 • 30-40% less error

**ECCV Best Paper** 

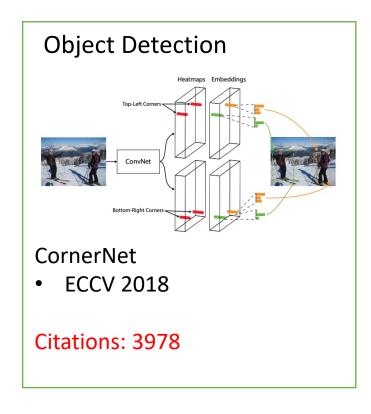


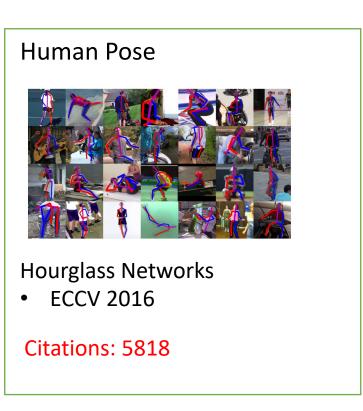


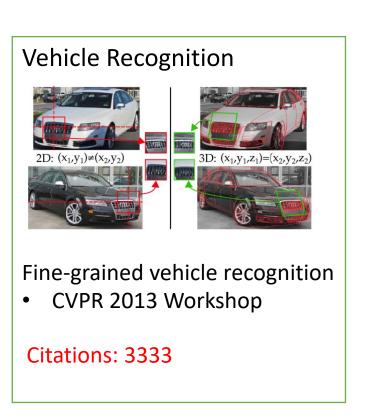


#### Capability 2: Object Recognition

- Extensive experience in object recognition
- PI was first author of ImageNet





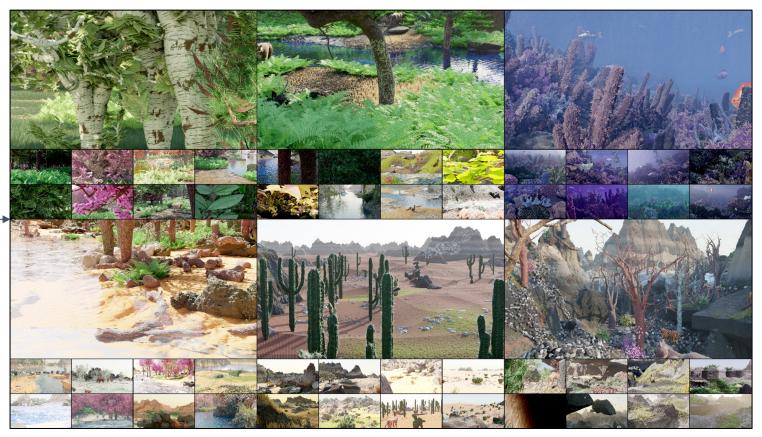


### Capability 3: Procedural Synthetic Data

- Infinigen: a procedural *generator* of infinite synthetic data (graphics-based)
  - CVPR 2023
  - infinigen.org



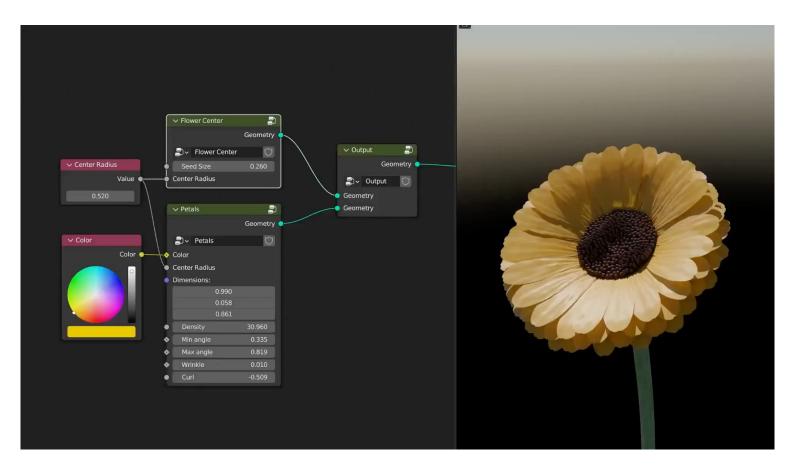
Random seeds + Optional user controls



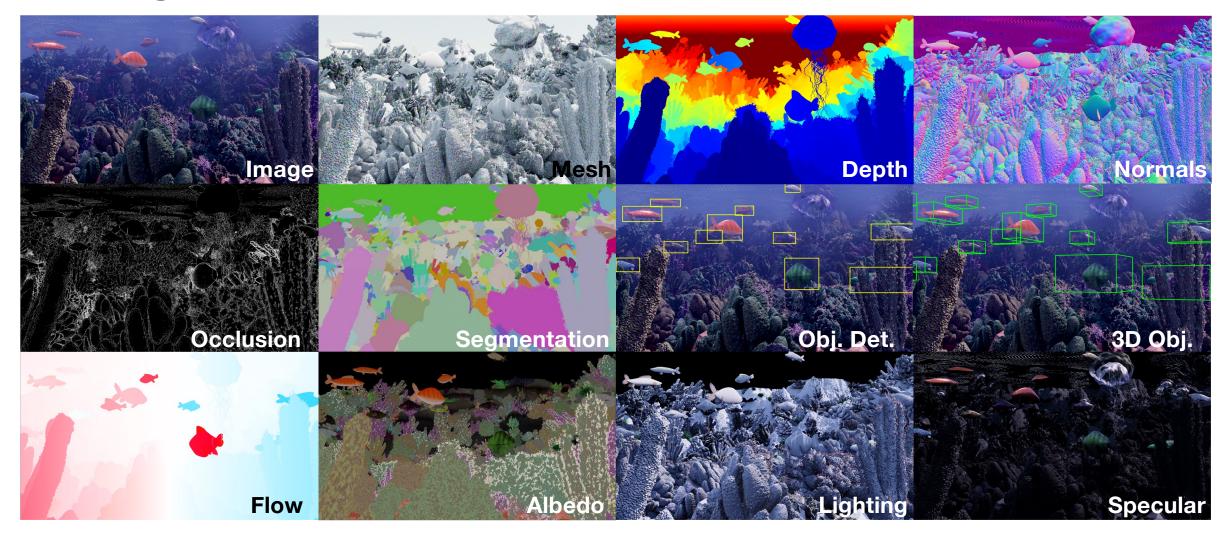
(Random sample of generated scenes)

#### Infinigen is 100% Procedural

- Generated from scratch using randomized mathematical rules
- Everything (shape, texture, material, lighting, arrangement, animation) is procedural
- No external assets
- No Al



### Infinigen creates automatic labels



# Infinigen is free and open-source (BSD)



https://github.com/princeton-vl/infinigen

## Customizing Infinigen for Video LINCS

- Data is often the bottleneck
- Infinite tailored synthetic data:
  - Custom procedural objects (e.g. vehicles) placed in diverse procedural scenes

